

Water Droplet Simulation

Math 164 Final Project

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Motivation (Why Do People Care?)

Example Applications

- Internal Combustion Engines
- Fire Suppression/Spray Cooling
- Aerosols
- Acid Rain
- Cloud Physics
- Heavy Rain and Ice Accretion on Aircraft Wings
- Ink Jet Printing
- Applications in Medicine (e.g. inhaled particles, including asthma inhalers)
- Manufacturing — droplet by molten droplet method
- Microencapsulation

Examples from *Dynamics of Droplets* by Frohn and Roth (2000)

Simplified Problem

From Prosperetti's 1977 paper

$$\frac{\partial \mathbf{U}}{\partial t} + (\mathbf{U} \cdot \nabla) \mathbf{U} = -\frac{1}{\rho} \operatorname{div} \sigma$$

$$\nabla \cdot \mathbf{U} = 0$$

with

$$\sigma_{ij} = -p \delta_{ij} + \mu \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right)$$

$\mathbf{U}$ = velocity field

t = time

ρ = density

σ = stress tensor

p = pressure

μ = viscosity

Even More Simplified

Assume surface of the form

$$r(\theta, \phi) = R + a_n(t) Y_n^m(\theta, \phi)$$

to get a new ODE

$$a_n'' + 2b_{n0} a_n' + \omega_{n0}^2 a_n + 2\beta_n b_{n0} \int_0^t Q_n(t-\tau) a_n'(\tau) d\tau = 0$$

R = average equilibrium radius

Y_n^m = spherical harmonic

a_n = amplitude

$$b_{n0} = (n-1)(2n+1)\nu/R^2$$

$$\omega_{n0}^2 = n(n-1)(n+2)\xi/\rho R^3$$

$$\beta_n = (n-1)(n+1)/(2n+1)$$

Q_n is defined by its Laplace transform

$$\tilde{Q}_n(p) = \left[1 + \frac{1}{2} \mathcal{J}_{n+\frac{3}{2}}(q) \right]^{-1}$$

$$q = R(p/\nu)^{1/2}$$

$$\mathcal{J}_{n+3/2}(q) = q I_{n+\frac{1}{2}}(q) / I_{n+\frac{3}{2}}(q)$$

Laplace Transformed Solution

■ Defined as:

$$\text{LaplaceTransform}[f[t], t, p] = \int_0^{\infty} f(t) e^{-p t} dt$$

■ Dimensionless variables

$\nu \rightarrow \epsilon$ Viscosity
 $t \rightarrow \tau$ Time
 $p \rightarrow s$ Laplace frequency

Initial Conditions

$$a_n(\tau = 0) \rightarrow 1$$

$$a_n'(\theta) \rightarrow u_0$$

■ Yields

```

atilde[s_, n_, ε_, u0_] := 1/s (1 + (u0 s - n (n - 1) (n + 2)) /
  (s^2 + 2 (n - 1) (2 n + 1) ε s + n (n - 1) (n + 2) + 2 (n - 1)^2 (n + 1) ε s Q[s, n, ε]));
Clear[Q]
Print["\n\n\n", "ã(s) = ",
  Style[1/s + 1/s (u0 s - const / (s^2 + ε s const + ε s Q[s, ε] const)) // TraditionalForm, FontSize -> 18]]
Q[s_, n_, ε_] := Module[{q = Sqrt[s/ε]},
  (2 BesselI[n + 3/2, q]) / (2 BesselI[n + 3/2, q] - q BesselI[n + 1/2, q])]

```

$$\tilde{a}(s) = (s u_0 - \text{const}) / \left(s (s^2 + \text{const} \epsilon s + \text{const} \epsilon Q(s, \epsilon) s) \right) + \frac{1}{s}$$

Numerical Inversion of Laplace Transform

■ Common Idea

Exploit multiple-precision computing to eliminate round-off errors and compute solution by brute force.

■ Fixed Talbot Algorithm

■ Main Idea

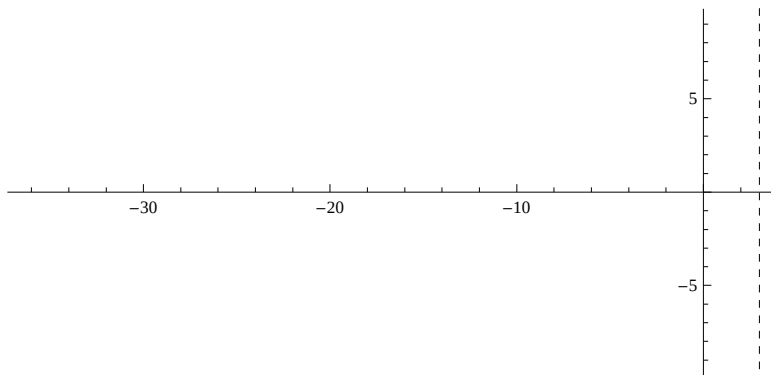
Deformation of the Bromwich integral:

$$\text{InverseLaplaceTransform}[F[p], p, t] = \frac{1}{2\pi i} \int_{\gamma-i\infty}^{\gamma+i\infty} F[p] e^{pt} dp$$

for some positive constant γ .

■ Deform the contour

$$p(\theta) = \gamma \theta (\cot(\theta) + i) \quad -\pi < \theta < +\pi$$



Then plug into inversion integral.

Approximate integral using trapezoidal rule with step size π/M

$$f(t, M) = \frac{\gamma}{M} \left(\frac{1}{2} F(\gamma) \exp(\gamma t) + \sum_{k=1}^{M-1} \text{Re}[\exp(t p(\theta_k)) F(p(\theta_k)) (p'(\theta_k)) / (i \gamma)] \right)$$

$$\theta_k = k \pi / M$$

By numerical experiment

$$\gamma = \frac{2M}{5t}$$

where M is the number of terms to be summed when calculating the integral.

■ The function

```
FT[F_, t_, M_] := Module[{np, r, S, theta, sigma}, np = Max[M, $MachinePrecision];
  r = SetPrecision[2 M / (5 t), np];
  S = r theta (Cot[theta] + I);
  sigma = theta + (theta Cot[theta] - 1) Cot[theta];
  (r / M) Plus @@ Append[Table[Re[Exp[t S] (1 + I sigma) F[S]],
    {theta, Pi / M, (M - 1) Pi / M, Pi / M}], (1 / 2) Exp[r t] F[r]]]
```

Inversion Continued

■ Gaver Functionals (GWR) Algorithm

Exact solution to inverse problem Post-Widder formula

$$\phi_k(t) = \frac{(-1)^k}{k!} \left(\frac{k}{t}\right)^{k+1} F^{(k)}\left(\frac{k}{t}\right)$$

where $F^{(k)}$ denotes the k th derivative and

$$F(p) = \mathcal{L}[f(t)]$$

Then $\phi_k(t) \rightarrow f(t)$ as $k \rightarrow \infty$

Approximate using difference formulas.

$$f_k(t) = \frac{\alpha k}{t} \binom{2k}{k} \sum_{j=0}^k (-1)^j \binom{k}{j} F((k+j)\alpha/t)$$

where $\alpha = \log(2)$.

Gaver functionals are a recursive method to calculate f_k but converge slowly.

Use Wynn rho convergence acceleration algorithm to get acronym GWR

■ The function

```

GWR[F_, t_, M_: 32, precin_: 0] := Module[
  {M1, G0, Gm, Gp, best, expr,  $\tau$  = Log[2] / t, Fi, broken, prec},
  If[precin <= 0, prec = 21 M / 10, prec = precin];
  If[prec <= $MachinePrecision, prec = $MachinePrecision];
  broken = False;
  If[Precision[ $\tau$ ] < prec,  $\tau$  = SetPrecision[ $\tau$ , prec]];
  Do[Fi[i] = N[F[i  $\tau$ ], prec], {i, 1, 2 M}];
  M1 = M;
  Do[
    G0[n - 1] =  $\tau$  (2 n)! / (n! (n - 1)!) Sum[
      Binomial[n, i] (-1)^i Fi[n + i], {i, 0, n}];
    If[Not[NumberQ[G0[n - 1]]], M1 = n - 1; G0[n - 1] =.; Break[]];
    , {n, 1, M}];
  Do[Gm[n] = 0, {n, 0, M1}];
  best = G0[M1 - 1];

  Do[
    Do[
      expr = G0[n + 1] - G0[n];
      If[Or[Not[NumberQ[expr]], expr == 0], broken = True; Break[]];
      expr = Gm[n + 1] + (k + 1) / expr;
      Gp[n] = expr;
      If[OddQ[k],
        If[n == M1 - 2 - k, best = expr]
      ];
      , {n, M1 - 2 - k, 0, -1}];
    If[broken, Break[]];
    Do[Gm[n] = G0[n]; G0[n] = Gp[n], {n, 0, M1 - k}];
    , {k, 0, M1 - 2}];
  best
]

```


The Results

```
Manipulate[Plot[GWR[atilde[#, 2,  $\epsilon$ , u0] &, t, ControlActive[10, 20]], {t, 0, 2},
  PlotPoints  $\rightarrow$  ControlActive[10, 15], MaxRecursion  $\rightarrow$  ControlActive[0, 2],
  PlotRange  $\rightarrow$  {- .5, 1.1}, AxesLabel  $\rightarrow$  {" $\tau$ ", " $a_2(\tau)$ "},
  {{ $\epsilon$ , 3 / 10}, 1 / 10, 1, 1 / 10}, {{u0, 3 / 10}, 0, 1, 1 / 10}]
```

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Pretty Pictures

■ Define functions

```

a[0, ___] := 1;
a[t_, n_: 2, ε_: 3/10, u0_: 0, M_: 32] :=
  GWR[atilde[#, n, ε, u0] &, Rationalize[t, 10-M], M]
Water = {Opacity[.8], Lighter[Blue, .35], Specularity[.7]};
r[t_, θ_, φ_, n_: 2, ε_: 3/10, u0_: 0, M_: 10] :=
  1 + a[Rationalize[t, 10-M], n, ε, u0, M] SphericalHarmonicY[n, 0, θ, φ];
SetOptions[SphericalPlot3D, {PlotPoints → 15, MaxRecursion → 1, Mesh → None,
  Lighting → "Neutral", PlotStyle → Water, PlotRange → 2, Axes → False, Boxed → False}];

```

■ Spherical Harmonic Initial Conditions

```

Manipulate[SphericalPlot3D[Evaluate[r[t, θ, φ, n, ε, u0, 10]],
  {θ, 0, π}, {φ, 0, 2 π}, Axes → False, Boxed → False], {{n, 2}, 2, 10, 1},
  {{ε, 3/10}, 1/10, 1, 1/10}, {{u0, 0}, 0, 1, 1/10}, {{t, 0}, 0, 2}]

```

■ Acorn-like Initial Condition

```

acorn[t_, θ_, φ_, ε_: 3/10, u0_: 0, M_: 10] :=
  1 + Sum[(-1)^n  $\frac{.3}{n^{5/4}}$  a[Rationalize[t, 10-M], 2 n + 1, ε, u0, M]
    SphericalHarmonicY[2 n + 1, 0, θ, φ], {n, 1, 13}]

acornlist = Table[SphericalPlot3D[
  Evaluate[acorn[t, θ, φ, 3/10, 0, 10]], {θ, 0, π}, {φ, 0, 2 π}], {t, 0, 3/2, 1/30}];
ListAnimate[acornlist]

```

Still To Do

- **Verify results with Prosperetti paper**
- **Bubbles**
- **Examine numerical algorithms in more detail**
- **Try to understand where ODE comes from**